

Valued Constraint Satisfaction Problem and Resilience in Database Theory

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Resilience of queries

database – a relational structure \mathfrak{A}

conjunctive query – a formula q of the form $\exists y_1, \dots, y_l (\psi_1 \wedge \dots \wedge \psi_m)$,
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Fixed conjunctive query q .

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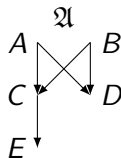
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Example: The resilience of

$$q = \exists x, y, z (R(x, y) \wedge R(y, z))$$

with respect to \mathfrak{A} is 1 – remove (C, E) .



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Goal: **Classify complexity** of **resilience** for all q .

Constraint satisfaction

Fixed τ -structure \mathfrak{A} (τ – finite relational signature)

Input: list of atomic τ -formulas (constraints)

Output:

- **CSP:** Decide whether there is a solution that satisfies **all** constraints.
- **MinCSP:** Find the **minimal number** of constraints to violate so that the remaining constraints are satisfiable simultaneously.
- **VCSP:** Find the **minimal cost** with which the constraints can be satisfied (each constraint comes with a cost depending on the chosen values).

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Observation: VCSP **generalizes** CSP and MinCSP.


Proof: Model the tuples in relations with cost 0 and outside with cost 1 (for MinCSP) or ∞ (for CSP).

Focus on VCSP

A **valued structure** Γ consists of:

- (countable) domain C
- (finite, relational) signature τ
- for each $R \in \tau$ of arity k , a function $R^\Gamma: C^k \rightarrow \mathbb{Q} \cup \{\infty\}$

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Definition (VCSP(Γ))

Input: $u \in \mathbb{Q}$, an expression

$$\phi(x_1, \dots, x_n) = \sum_i \psi_i,$$

where each ψ_i is an atomic τ -formula

Question: Is

$$\inf_{t \in C^n} \phi(t) \leq u \text{ in } \Gamma?$$

Example: Max-Cut as a VCSP

Input: $G = (V, E)$ – finite directed (multi)graph

Goal: Find a partition $A \cup B$ of V such that $E \cap (A \times B)$ is maximal.

Equivalently: $E \cap (A^2 \cup B^2 \cup B \times A)$ is minimal.

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Let Γ_{MC} be a valued structure where:

- $C = \{0, 1\}$
- $\tau = \{R\}$, R binary

$$R(x, y) = \begin{cases} 0 & \text{if } x = 0 \text{ and } y = 1 \\ 1 & \text{otherwise} \end{cases}$$

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Take vertices of G as variables. The size of a maximal cut of G is

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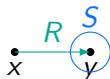
every instance of $\text{VCSP}(\Gamma_{MC})$ corresponds to a directed multigraph

$\rightsquigarrow \text{VCSP}(\Gamma_{MC})$ is the Max-Cut problem (NP-hard)

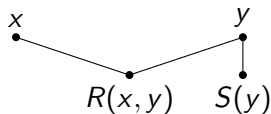
Translation to a dual problem

Example:

$$q := \exists x, y (R(x, y) \wedge S(y))$$



canonical structure

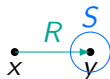


incidence graph $I(q)$

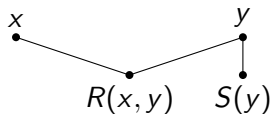
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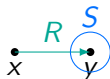
Let q be a query and \mathcal{Q} its canonical structure. If $I(q)$ is connected, then there exists a structure \mathfrak{B}_q , such that for every finite \mathfrak{A} :

$$\mathfrak{A} \not\models q \Leftrightarrow \mathcal{Q} \not\prec \mathfrak{A} \Leftrightarrow \mathfrak{A} \rightarrow \mathfrak{B}_q$$

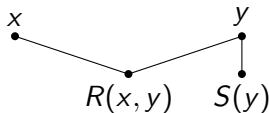
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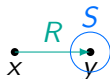
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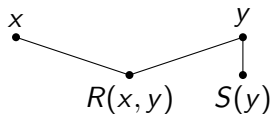
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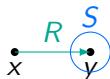
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- \mathfrak{B}_q can be chosen *finite* iff q is homomorphically equivalent to q' such that $I(q')$ is a *tree*. (Nešetřil, Tardiff '00; Larose, Loten, Tardiff '07)

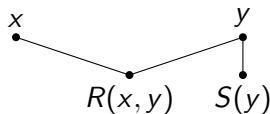
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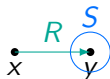
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oligomorphic – countable domain B_q and the action of $\text{Aut}(\mathfrak{B}_q)$ on B_q^n has *finitely many orbits* for every $n \geq 1$

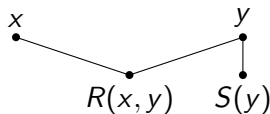
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Example: For every finite directed graph G we have:

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Connection of resilience and VCSPs

query q with $I(q)$ connected (WLOG) \rightsquigarrow obtain the dual structure $\mathfrak{B}_q \rightsquigarrow$ turn it into a valued structure Γ_q with cost functions taking values 0 and 1

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$\mathfrak{B}_q \rightsquigarrow \Gamma_{\text{MC}} = (\{0, 1\}; R)$

Resilience of $q = \text{VCSP}(\Gamma_{\text{MC}}) = \text{Max-Cut}$ is NP-hard

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Remark: We have to consider **bag databases** – a database \mathfrak{A} might contain a **tuple** with **multiplicity** > 1 (differs from the original setting).

Example: Input $R(x, y) + R(x, y)$ for **VCSP**(Γ) corresponds to a database with multiplicity 2 for $R(x, y)$.

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Corollary: $I(q)$ is a tree $\Rightarrow \Gamma_q$ can be taken finite

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For a *finite-domain* valued structure Γ , $\text{VCSP}(\Gamma)$ is in *P* or *NP-complete*.

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Question: For **general queries**, choose \mathfrak{B}_q such that $\text{Aut}(\mathfrak{B}_q)$ is oligomorphic \Rightarrow **finitely many** orbits of n -tuples for every n .

Can we use some results for finite domains?

Hard resilience problems

pp-construction – a notion of ‘expressing’ one valued structure in another
(generalizes pp-constructions for classical structures)

Fact: If $\text{Aut}(\Gamma)$ is **oligomorphic** and Γ **pp-constructs** Δ , then $\text{VCSP}(\Delta)$ **reduces** to $\text{VCSP}(\Gamma)$ in **poly-time**.

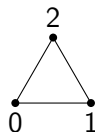
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K_3 is the valued structure on $\{0, 1, 2\}$ with single binary relation E defined:

$$E(x, y) = \begin{cases} 0 & \text{if } x \neq y \\ \infty & \text{if } x = y \end{cases}$$



Observation: $\text{VCSP}(K_3)$ is the 3-colorability problem and hence NP-hard.

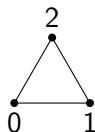
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Fractional polymorphisms

polymorphism of a relational structure $\mathfrak{A} - f : A^n \rightarrow A$ such that for all relations R of \mathfrak{A} and $t^1, \dots, t^n \in R$, $f(t^1, \dots, t^n) \in R$ (applied row-wise)

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Example: The operation \min is a polymorphism of $(\mathbb{Q}; <)$.

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Definition (fractional polymorphism)

A **fractional polymorphism** of Γ of arity n is a **probability distribution** ω on the maps $f : C^n \rightarrow C$ such that for every k -ary $R \in \tau$ and $t^1, \dots, t^n \in C^k$

$$\underbrace{E_\omega[f \mapsto R(f(t^1, \dots, t^n))]}_{\text{expected value}} \leq \underbrace{\frac{1}{n} \sum_{j=1}^n R(t^j)}_{\text{arithmetic mean}} \quad (\omega \text{ improves } R).$$

Tractability conjecture

Known for finite-domain VCSPs:

Theorem

Γ – a *finite-domain* valued structure

- If Γ *does not pp-construct* K_3 , then Γ has *cyclic fractional polymorphism* (essentially [Kozik, Ochremiak '15]).
- If Γ has a *cyclic fractional polymorphism*, then $\text{VCSP}(\Gamma)$ is in P [Kolmogorov, Krokhin, Rolínek '15].

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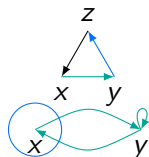
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Conjecture: If Γ_q *does not pp-construct* K_3 , then the *tractability theorem* *applies* and $\text{VCSP}(\Gamma_q)$ and hence *resilience* of q is in P .

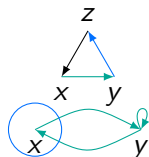
Examples

- $q_{MC} := \exists x, y, z (R(x, y) \wedge R(y, z))$
- $q_{path} := \exists x, y, z (R(x, y) \wedge S(y, z))$
- $q_{\Delta} := \exists x, y, z (R(x, y) \wedge S(y, z) \wedge T(z, x))$
- $q_{new} := \exists x, y (S(x) \wedge R(x, y) \wedge R(y, x) \wedge R(y, y))$



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query	complexity	VCSP proof
q_{MC}	NP-hard (FGIM '20)	Max-Cut/pp-constructs K_3
q_{path}	P (MG)	binary cyclic frac. polymorphism
q_{Δ}	NP-hard (FGIM '15)	pp-constructs K_3
q_{new}	P (BLS)	binary pseudo cyclic frac. polymorphism

References:

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