

# Forbidden Tournaments and the Orientation (Completion) Problem

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# Oriented expressions of graph classes

## Example 1 (Robbins 1939)

A graph  $G$  is 2-edge-connected if and only if it admits a strongly connected orientation.

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## Example 3 (Roy-Gallai-Hasse-Vitaver Theorem)

A graph  $G$  is  $k$ -colourable if and only if it admits an orientation with no directed walk of length  $k$ .

# Oriented expressions of graph classes

## Example 2 (Standard definition)

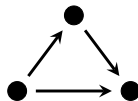
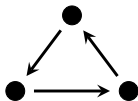
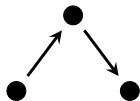
A graph  $G$  is a comparability graph if and only if it admits an  $\mathcal{F}$ -free orientation.



# Oriented expressions of graph classes

## Example 3 ( $k = 2$ of RGHV-Theorem)

A graph  $G$  is a bipartite graph if and only if it admits an  $\mathcal{F}$ -free orientation.



# Oriented expressions of graph classes

## Example 4 (Skrien 1982)

A connected graph  $G$  is a proper circular-arc graph if and only if it admits an  $\mathcal{F}$ -free orientation.

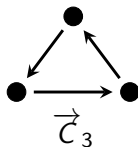
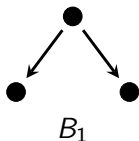


# Oriented expressions of graph classes

## Characterization Problem

Given a finite set of oriented graphs  $\mathcal{F}$  characterize the class of graphs that admit an  $\mathcal{F}$ -free orientation (e.g., list their minimal obstructions).

- ▶ Orientations of  $P_3$  (Skrien 1982).
- ▶ Oriented graphs on 3 vertices (G.P. and Hernández-Cruz 2021).
- ▶ Open cases:  $\mathcal{F} = \{B_1\}$  and  $\mathcal{F} = \{B_1, \vec{C}_3\}$ .



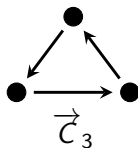
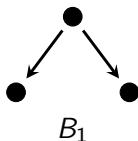


# Oriented expressions of graph classes

## Complexity Problem

Given a finite set of oriented graphs  $\mathcal{F}$ , determine the complexity of deciding if an input graph  $G$  admits an  $\mathcal{F}$ -free orientation?

- ▶ In P when  $\mathcal{F}$  is a set of oriented graphs on 3 vertices (Urrutia and Gavril 1992, Bang-Jensen and Gutin 2007, G.P. and Hernández-Cruz 2021).
- ▶ Open case:  $\mathcal{F} = \{B_1, \vec{C}_3\}$ .

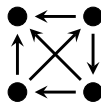
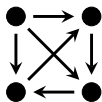


# Oriented expressions of graph classes

## Complexity Problem (completion version)

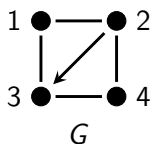
Given a finite set of oriented graphs  $\mathcal{F}$ , determine the complexity of deciding if an input partially oriented graph  $G$  can be completed to an  $\mathcal{F}$ -free oriented graph?

- ▶ Orientations of  $P_3$  always in  $P$  (Bang-Jensen, Huang, Zhu, 2017).
- ▶  $T_3$ -free orientation completion problem in  $P$ .
- ▶ (Bang-Jensen, Huang, Zhu) NP-complete for:



# Complexity Classification

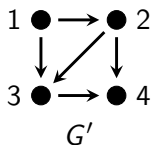
# Complexity Classification



Code orientation completions of  $G$  as solutions to the sys. lin. eq. over  $\mathbb{Z}_2$

$$x_{ij} + x_{ji} = 0 \text{ for } ij \in U$$

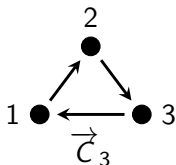
$$x_{ij} = 1 \text{ for } ij \in E$$



$$x_{12} = 1, x_{13} = 1, x_{23} = 1, x_{24} = 1, x_{34} = 1$$

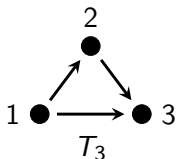
$$x_{21} = 0, x_{31} = 0, x_{32} = 0, x_{42} = 0, x_{43} = 0$$

# Complexity Classification



For each triangle  $i, j, k$  the following equality holds:

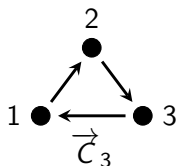
$$x_{ij} + x_{jk} = 0.$$



There exists a triangle  $i, j, k$  such that the following equality holds:

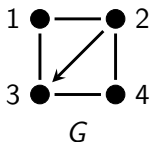
$$x_{ij} + x_{jk} = 1 \text{ for instance } x_{23} + x_{31} = 1.$$

# Complexity Classification



For each triangle  $i, j, k$  the following equality holds:

$$x_{ij} + x_{jk} = 0.$$



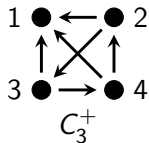
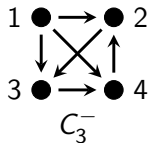
Code  $T_3$ -free orientation completions of  $G$  as solutions to

$$x_{ij} + x_{ji} = 0 \text{ for } ij \in U$$

$$x_{ij} = 1 \text{ for } ij \in E$$

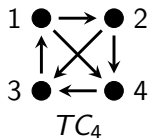
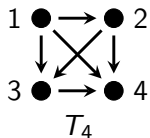
$$x_{ij} + x_{jk} = 0 \text{ for } ijk \in T$$

# Complexity Classification



For each  $i, j, k, l$  in  $C_3^-$  and in  $C_3^+$

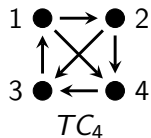
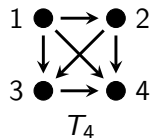
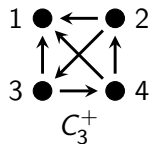
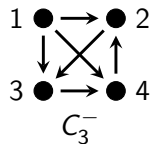
$$x_{ij} + x_{jk} + x_{kl} + x_{li} = 0.$$



$$x_{12} + x_{23} + x_{34} + x_{41} = 1 \text{ in } T_4$$

$$x_{12} + x_{23} + x_{34} + x_{41} = 1 \text{ in } TC_4$$

# Complexity Classification



$\mathcal{F}$ -free orientation completions of  $G$

$$x_{ij} + x_{ji} = 0 \text{ for } ij \in U$$

$$x_{ij} = 1 \text{ for } ij \in E$$

$$x_{ij} + x_{jk} + x_{kl} + x_{li} = 0 \text{ for } ijkl \in K_4(G).$$

$$x_{12} + x_{23} + x_{34} + x_{41} = 1 \text{ in } T_4$$

$$x_{12} + x_{23} + x_{34} + x_{41} = 1 \text{ in } TC_4$$



# Complexity Classification

## NP-hard example

The  $\vec{C}_3$ -free orientation completion problem is NP-complete, via reduction from not-all-equal 3-sat

### not-all-equal 3-sat problem

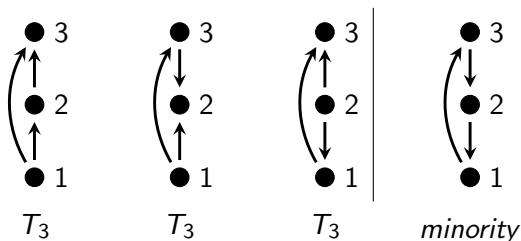
Input:  $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_k \vee y_k \vee z_k)$

Solution: a function  $f: V \rightarrow \{0, 1\}$  such that

$$(f(x_i), f(y_i), f(z_i)) \in \{0, 1\}^3 \setminus \{(0, 0, 0), (1, 1, 1)\}.$$



# Complexity Classification



- ▶  $\vec{C}_3$ -free tournaments **are not** preserved by the *minority* operation.
- ▶  $T_3$ -free tournaments **are** preserved by the *minority* operation.

# Complexity Classification

## Theorem (Bodirsky, G.P., 23+)

For every finite set of finite tournaments  $\mathcal{F}$  one of the following cases holds.

1.  $\mathcal{F}_f$  is preserved by the minority operation. In this case, the  $\mathcal{F}$ -free orientation completions of a partially oriented graph  $G$  correspond to the solution space of a system of linear equations over  $\mathbb{Z}_2$ .
2. Otherwise,  $\mathcal{F}$ -free orientation completion problem is NP-complete.

In the first case, the  $\mathcal{F}$ -free orientation completion problem is in P.

# Complexity Classification

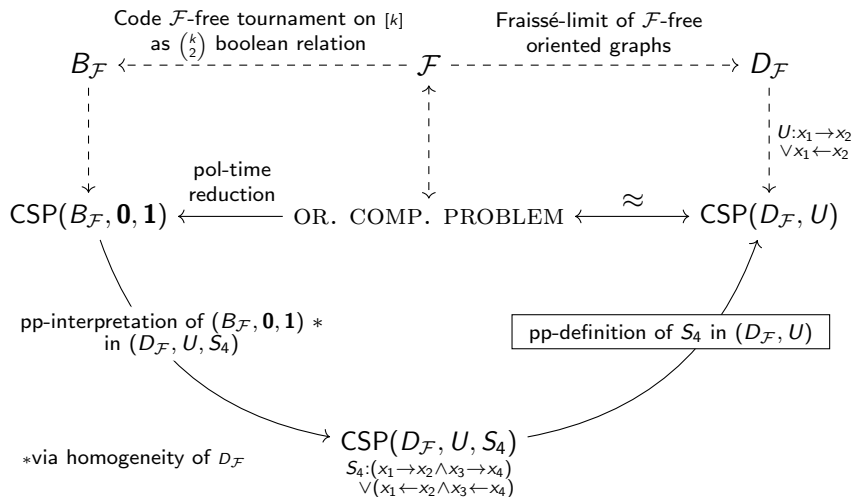
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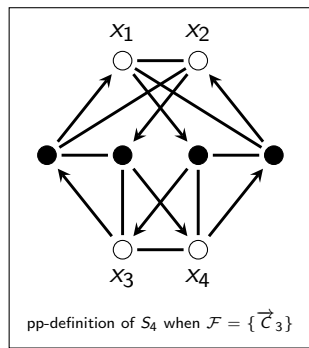
1.  $\mathcal{F}$  contains no transitive tournament. In this case, every graph admits an  $\mathcal{F}$ -free orientation.
2.  $\mathcal{F}_f$  is preserved by the minority operation. In this case, the  $\mathcal{F}$ -free orientations of a graph  $G$  correspond to the solution space of a system of linear equations over  $\mathbb{Z}_2$ .
3. Otherwise,  $\mathcal{F}$ -free orientation problem is NP-complete.

In cases 1 and 2, the  $\mathcal{F}$ -free orientation problem is in P.

# Proof overview



# Proof overview



Essentially combinatorial

$D_{\mathcal{F}}$

$U: x_1 \rightarrow x_2$   
 $\vee x_1 \leftarrow x_2$

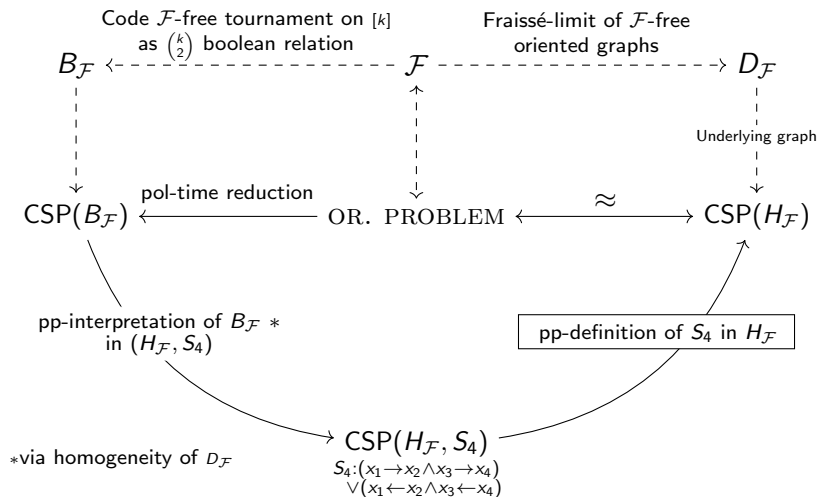
$\text{CSP}(D_{\mathcal{F}}, U)$

pp-definition of  $S_4$  in  $(D_{\mathcal{F}}, U)$

$\text{CSP}(D_{\mathcal{F}}, U, S_4)$

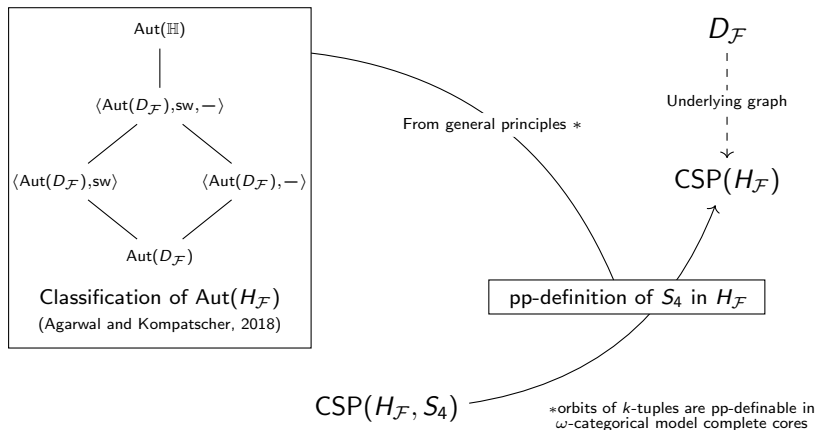
$S_4: (x_1 \rightarrow x_2 \wedge x_3 \rightarrow x_4)$   
 $\vee (x_1 \leftarrow x_2 \wedge x_3 \leftarrow x_4)$

# Proof overview





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# Thank you!

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