

Forbidden Tournaments and the Orientation (Completion) Problem

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joint work with Manuel Bodirsky

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Atlantic Graph Theory seminar

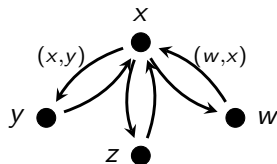
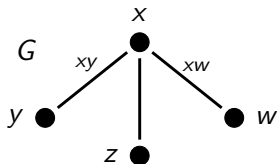


ERC Synergy Grant POCOCOP (GA 101071674)

General setting

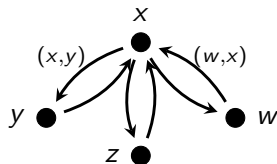
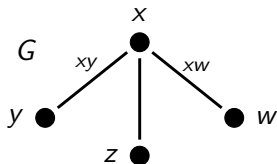
General setting

Simple graphs (possibly infinite)

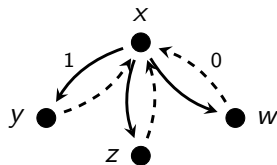
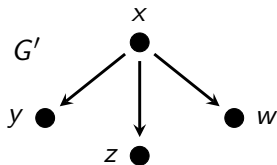


General setting

Simple graphs (possibly infinite)

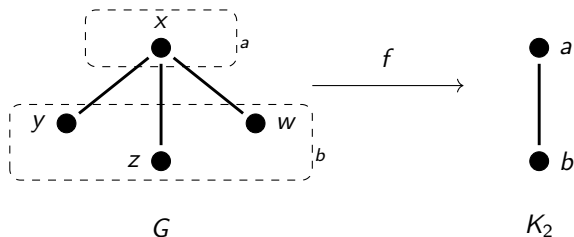


Oriented graphs (possibly infinite)



General setting

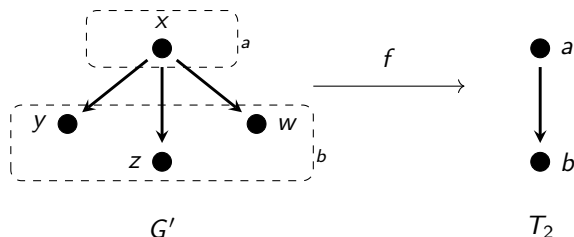
Homomorphism: Edge-preserving function $f: V(G) \rightarrow V(H)$



Observation: A graph G is k -colourable if and only if $G \rightarrow K_k$

General setting

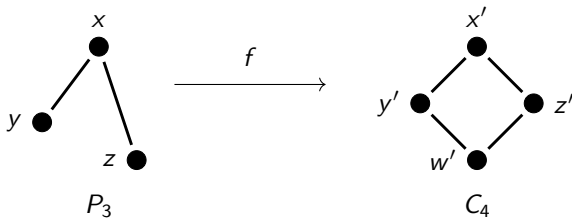
Homomorphism: Arc-preserving function $f: V(G) \rightarrow V(H)$



Observation: An oriented graph G' has a directed walk on k vertices if and only if $\vec{P}_k \rightarrow G'$

General setting

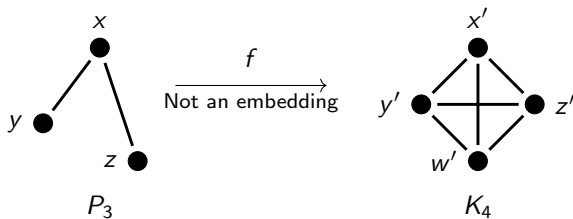
Embedding: Injective homomorphism $f: G \rightarrow H$ that preserves non-edges



Observation: $G < H$ if and only if H contains G as an *induced subgraph* (up to isomorphism)

General setting

Embedding: Injective homomorphism $f: G \rightarrow H$ that preserves non-edges



General setting

Hereditary class (property): A class \mathcal{C} such that for each $G \in \mathcal{C}$ if $H < G$ then $H \in \mathcal{C}$

- ▶ Bipartite graphs
- ▶ Triangle-free graphs
- ▶ Forests
- ▶ H -colourable graphs
- ▶ Circular-arc graphs

F-free graphs: A graph G is \mathcal{F} -free if G does not contain any $F \in \mathcal{F}$ as induced subgraph

General setting

Theorem template (for hereditary classes): A graph G is a YYY -graph if and only if G is \mathcal{F}_Y -free

- ▶ Triangle-free graphs — K_3
- ▶ Forests — C_n with $n \geq 3$
- ▶ Perfect graphs — Odd holes and odd anti-holes
- ▶ Trivially-perfect graphs — C_4 and P_4
- ▶ Bipartite graphs — Odd cycle
- ▶ k -colourable graphs — Unknown for $k \geq 3$

Oriented expressions of graph classes

Oriented expressions of graph classes

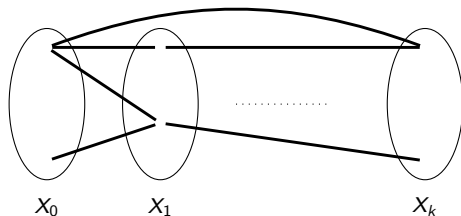
Roy-Gallai-Hasse-Vitaver Theorem (60s)

A graph G is k -colourable if and only if there is an orientation G' of G with no directed walk on $k + 1$ vertices.

Oriented expressions of graph classes

Roy-Gallai-Hasse-Vitaver Theorem (60s)

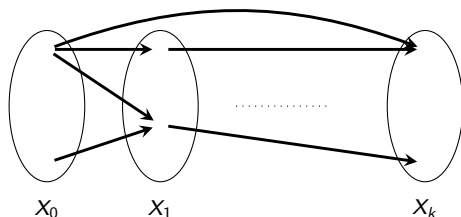
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Oriented expressions of graph classes

Roy-Gallai-Hasse-Vitaver Theorem (60s)

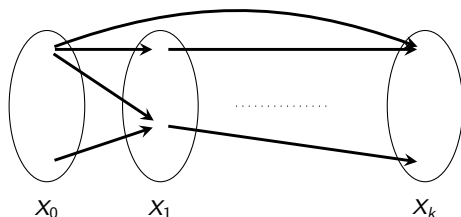
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Oriented expressions of graph classes

Roy-Gallai-Hasse-Vitaver Theorem (60s)

A graph G is k -colourable if and only if there is an orientation G' of G with no directed walk on $k + 1$ vertices.



Conversely, let $c(v)$ be the length of the largest directed walk of G' starting in v . If $(x, y) \in E(G')$, then $c(x) > c(y)$. Thus, if $xy \in E(G)$, then $c(x) > c(y)$ or $c(y) > c(x)$.

Oriented expressions of graph classes

Comparability graphs

The comparability graph of a poset (P, \leq) is the graph with vertex set P and $xy \in E$ if x and y are comparable in (P, \leq) .

A graph G is a comparability graph if G is the comparability graph of some poset P .

Theorem: A graph G is a comparability graph if and only if it is an F -free graph¹

$(XF_1^{2n+3}, XF_5^{2n+3}, XF_6^{2n+2}, \overline{C_{n+6}}, \overline{T_2}, X_2, X_3, X_{30}, X_{31}, X_{32}, X_{33}, X_{34}, X_{35}, X_{36}, \text{co-}XF_2^{n+1}, \text{co-}XF_4^n, \text{co-}XF_4^n, \text{odd-hole})$ -free

¹Screenshot: graphclasses.org

Oriented expressions of graph classes

Comparability graphs

The comparability graph of a poset (P, \leq) is the graph with vertex set P and $xy \in E$ if x and y are comparable in (P, \leq) .

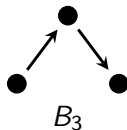
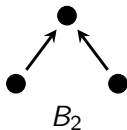
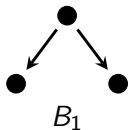
A graph G is a comparability graph if G is the comparability graph of some poset P .

Observation: A graph G is a comparability graph if and only if it admits an \mathcal{F} -free orientation



Oriented expressions of graph classes

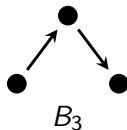
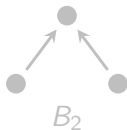
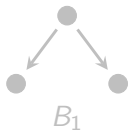
Skrien (1982)



- ▶ Comparability graphs
- ▶ Trivially perfect graphs
- ▶ Proper circular-arc graphs
- ▶ Perfectly orientable graphs

Oriented expressions of graph classes

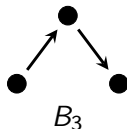
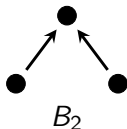
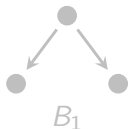
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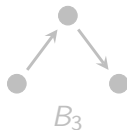
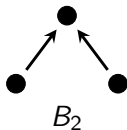
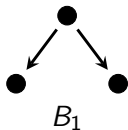
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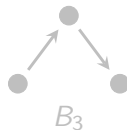
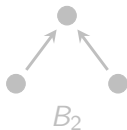
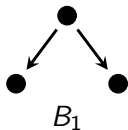
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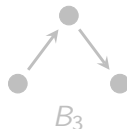
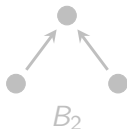
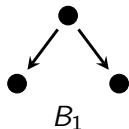
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Oriented expressions of graph classes

Skrien (1982)



Perfectly orientable graphs

Gavril and Urrutia (1992): polynomial-time recognition algorithm

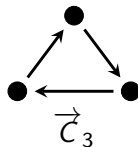
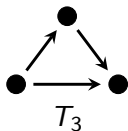
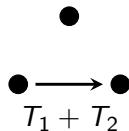
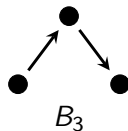
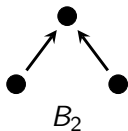
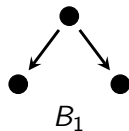
Hartinger and Milanic (2016–2017): towards structural characterization

General algorithm

Bang-Jensen and Gutin (2009): uniform reduction to 2-SAT

Oriented expressions of graph classes

Extending Skrien



Oriented expressions of graph classes

List of graph classes expressible by forbidden orientations on three vertices:

- ▶ Perfectly orientable graphs
- ▶ Comparability graphs
- ▶ Odd closed strip hom.-free graphs
- ▶ Proper circular-arc graphs
- ▶ Trivially perfect graphs
- ▶ Transitive-perfectly orientable graphs
- ▶ Unicyclic graphs
- ▶ Triangle-free unicyclic graphs
- ▶ 3-colourable comparability graphs
- ▶ Triangle-free graphs
- ▶ Clusters
- ▶ Proper Helly circular-arc graphs
- ▶ Triangle-free proper circular-arc graphs
- ▶ Paths and cycles
- ▶ Paths and cycles but no triangles
- ▶ Triangles and stars
- ▶ Star forests
- ▶ Stars and empty graphs
- ▶ Matchings with isolated vertices
- ▶ Empty graphs and K_2
- ▶ Bipartite graphs
- ▶ Complete bipartite graphs
- ▶ Complete 3-partite graphs
- ▶ $K_{2,3}$ -free complete multipartite graphs
- ▶ Complete multipartite graphs
- ▶ All graphs

Oriented expressions of graph classes

Polynomial time recognition cases:

- ▶ Perfectly orientable graphs
- ▶ Comparability graphs
- ▶ Odd closed strip hom.-free graphs
- ▶ Proper circular-arc graphs
- ▶ Trivially perfect graphs
- ▶ Transitive-perfectly orientable graphs?
- ▶ Unicyclic graphs
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Parallel research lines

Linear orderings: Damaschke (1990); Duffus, Ginn, and Rödl (1995); Hell, Mohar, and Rafiey (2014); Feuilloley and Habib (2021 –2023).

Circular orderings: Tucker (1972); G.P., Hell, and Hernández-Cruz (2023).

Tree-layouts: Paul and Protopapas (2023).

Vertex/edge colourings: Feder and Vardi (1999), Bodirsky, Madelaine, and Mottet (2021), Barsukov (2023), Bok, G.P., Hernández-Cruz, Jedličková (2024).

Three generic problems

Characterization Problem

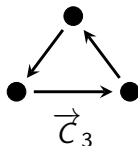
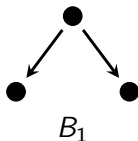
Given a finite set of oriented graphs \mathcal{F} characterize the class of graphs that admit an \mathcal{F} -free orientation (e.g., list their minimal obstructions).

Three generic problems

Characterization Problem

Given a finite set of oriented graphs \mathcal{F} characterize the class of graphs that admit an \mathcal{F} -free orientation (e.g., list their minimal obstructions).

- ▶ Orientations of P_3 (Skrien 1982).
- ▶ Perfectly orientable graphs (Hartinger and Milanic 2016, 2017).
- ▶ Oriented graphs on 3 vertices (G.P. and Hernández-Cruz 2021).
- ▶ Open cases: $\mathcal{F} = \{B_1\}$ and $\mathcal{F} = \{B_1, \vec{C}_3\}$.



Three generic problems

Characterization Problem

Given a hereditary class of graphs \mathcal{C} , determine if there is a finite set of oriented graphs \mathcal{F} such that, a graph G admits an \mathcal{F} -free orientation if and only if $G \in \mathcal{C}$.

Three generic problems

Characterization Problem

Given a hereditary class of graphs \mathcal{C} , determine if there is a finite set of oriented graphs \mathcal{F} such that, a graph G admits an \mathcal{F} -free orientation if and only if $G \in \mathcal{C}$.

Positive results:

- ▶ Roy-Gallai-Hasse-Vitaver Theorem (1960 – 1968)
- ▶ C_{2n+1} -colourable graphs (G.P. and Hernández-Cruz 2021)
- ▶ $\overline{C_{2n+1}}$ -colourable graphs (Gujgiczer and G.P. 2023+)
- ▶ Orientations *might be good* at distinguishing H -colourings

Three generic problems

Characterization Problem

Given a hereditary class of graphs \mathcal{C} , determine if there is a finite set of oriented graphs \mathcal{F} such that, a graph G admits an \mathcal{F} -free orientation if and only if $G \in \mathcal{C}$.

Negative results:

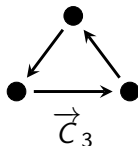
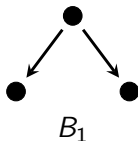
- ▶ Forests
- ▶ Chordal graphs
- ▶ Even-hole free graphs
- ▶ Orientations *are bad* at distinguishing cycles (G.P. and Hernández-Cruz 22)

Three generic problems

Complexity Problem

Given a finite set of oriented graphs \mathcal{F} , determine the complexity of deciding if an input graph G admits an \mathcal{F} -free orientation

- ▶ In P when \mathcal{F} is a set of oriented graphs on 3 vertices (Urrutia and Gavril 1992, Bang-Jensen and Gutin 2007, G.P. and Hernández-Cruz 2021).
- ▶ Open case: $\mathcal{F} = \{B_1, \vec{C}_3\}$.



Three generic problems

Complexity Problem (completion version)

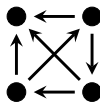
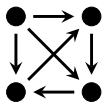
Given a finite set of oriented graphs \mathcal{F} , determine the complexity of deciding if an input partially oriented graph G can be completed to an \mathcal{F} -free oriented graph?

Three generic problems

Complexity Problem (completion version)

Given a finite set of oriented graphs \mathcal{F} , determine the complexity of deciding if an input partially oriented graph G can be completed to an \mathcal{F} -free oriented graph?

- ▶ Orientations of P_3 always in P (Bang-Jensen, Huang, Zhu, 2017).
- ▶ T_3 -free orientation completion problem in P .
- ▶ (Bang-Jensen, Huang, Zhu) NP-complete for:



Three generic problems

Task for today

Given a finite set of tournaments \mathcal{F} :

1. Understand the complexity of the \mathcal{F} -free orientation problem.
2. Understand the complexity of the \mathcal{F} -free orientation completion problem.

Computational complexity

Computational complexity

Boolean satisfiability problem

Input: $(x_1^1 \vee x_2^1 \vee \dots \vee x_{i_1}^1) \wedge \dots \wedge (x_1^n \vee x_2^n \vee \dots \vee x_{i_n}^n)$

Question: Is the instance satisfiable?

First known problem to be NP-complete (Cook 1969, Levin 1970)

k-SAT

Input: $(x_1^1 \vee x_2^1 \vee \dots \vee x_k^1) \wedge \dots \wedge (x_1^n \vee x_2^n \vee \dots \vee x_k^n)$

Question: Is the instance satisfiable?

In P if $k \leq 2$, and otherwise NP-complete.

Computational complexity

Ladner's Theorem (1975)

If $P \neq NP$, then there are NP-intermediate problems, i.e., problems in NP which are not solvable in polynomial-time nor NP-complete.

Candidate for NPI: Graph isomorphism problem.

Computational complexity

NAE 3-SAT

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \notin \{(0, 0, 0), (1, 1, 1)\}$?

Horn-SAT

Input: $(\neg x_1^1 \vee x_2^1 \vee \cdots \vee x_k^1) \wedge \cdots \wedge (\neg x_1^n \vee x_2^n \vee \cdots \vee x_k^n)$

Question: Is the instance satisfiable?

1-in-3 SAT

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \in \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$?

Computational complexity

NAE 3-SAT

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \notin \{(0, 0, 0), (1, 1, 1)\}$?

Horn-SAT

Input: $(\neg x_1^1 \vee x_2^1 \vee \cdots \vee x_k^1) \wedge \cdots \wedge (\neg x_1^n \vee x_2^n \vee \cdots \vee x_k^n)$

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Computational complexity

NAE 3-SAT

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \notin \{(0, 0, 0), (1, 1, 1)\}$?

Horn-SAT

Input: $(\neg x_1^1 \vee x_2^1 \vee \cdots \vee x_k^1) \wedge \cdots \wedge (\neg x_1^n \vee x_2^n \vee \cdots \vee x_k^n)$

Question: Is the instance satisfiable?

1-in-3 SAT

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \in \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$?

Computational complexity

Linear equations (mod 2)

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \in \{(0, 0, 0), (1, 1, 0), (1, 0, 1), (0, 1, 1)\}$? (i.e., solutions to the system $x_i + y_i + z_i = 0$)

Computational complexity

Linear equations (mod 2)

Input: $(x_1 \vee y_1 \vee z_1) \wedge \cdots \wedge (x_n \vee y_n \vee z_n)$

Question: Is there a solution such that $(x_i, y_i, z_i) \in \{(0, 0, 0), (1, 1, 0), (1, 0, 1), (0, 1, 1)\}$? (i.e., solutions to the system $x_i + y_i + z_i = 0$)

Schaefer's dichotomy theorem (moral version)

Every Boolean satisfaction problem $\text{CSP}(\mathbb{B})$ is either in P or NP-complete. Moreover, if it is not NP-complete, then $\text{CSP}(\mathbb{B})$ is equivalent to one of the following cases:

- ▶ trivial-SAT
- ▶ Horn-SAT
- ▶ 2-SAT
- ▶ linear equations modulo 2

Classifications in graph theory

Folk: The k -colouring problem is in P if $k \leq 2$, and otherwise it is NP-complete

Hell-Nešetřil (1990): If H is a finite graph, then the H -colouring problem is in P if H is bipartite, otherwise it is NP-complete.

Barto, Kozik, Niven (2009): If D is a (core) digraph with no sources nor sinks, then $\text{CSP}(D)$ is in P if every component of D is a directed cycle, and NP-complete otherwise (conjectured by Bang-Jensen and Hell 1990).

CSP dichotomy (Bulatov 2017, Zhuk 2017): If D is a finite digraph, then $\text{CSP}(D)$ is either polynomial-time solvable or NP-complete (conjectured by Feder and Vardi 1999).

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Classifications in graph theory

Example 1: For every k there is a countable graph \mathbb{H}_k such a finite graph is an induced subgraph of \mathbb{H}_k if and only if G is K_k -free. In particular, $G \rightarrow \mathbb{H}_k$ if and only if G is K_k -free.

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Tractability conjecture (Bodirsky-Pinsker 2011): If D is a countable digraph and \blacksquare , then $\text{CSP}(D)$ is either polynomial-time solvable or NP-complete.

Classifications in graph theory

Fact (Fraïssé's theorem): For every finite set of tournaments \mathcal{F} there is an infinite graph $D_{\mathcal{F}}$ such that an oriented graph G' is \mathcal{F} -free if and only if it is an induced oriented subgraph of $D_{\mathcal{F}}$.

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Observation: If $H_{\mathcal{F}}$ is the underlying graph of $D_{\mathcal{F}}$ and G is a finite graph, then G admits an \mathcal{F} -free orientation if and only if $G \rightarrow H_{\mathcal{F}}$.

Classifications in graph theory

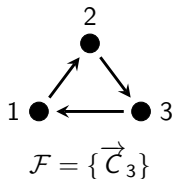
Fact (Fraïssé's theorem): For every finite set of tournaments \mathcal{F} there is an infinite graph $D_{\mathcal{F}}$ such that an oriented graph G' is \mathcal{F} -free if and only if it is an induced oriented subgraph of $D_{\mathcal{F}}$.

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Task of today: Is there dichotomy for $\text{CSP}(H_{\mathcal{F}})$?

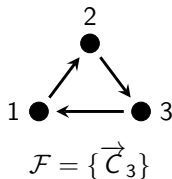
The \mathcal{F} -free orientation problem

Example 1: Every tournament in \mathcal{F} has a directed cycle



The \mathcal{F} -free orientation problem

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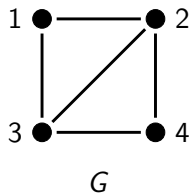
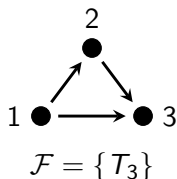


Remark: \mathcal{F} -free orientation problem is trivial

But: Orientation completion not necessarily trivial.

The \mathcal{F} -free orientation problem

Example 2: T_3 -free orientation (completion) problem.

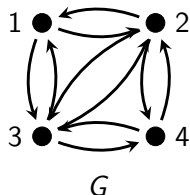
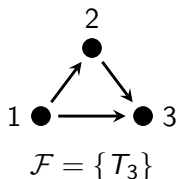


Code orientations of G as solutions to the sys. lin. eq. over \mathbb{Z}_2

$$x_{ij} + x_{ji} = 0 \text{ for } ij \in E$$

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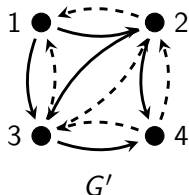
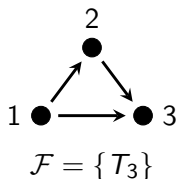


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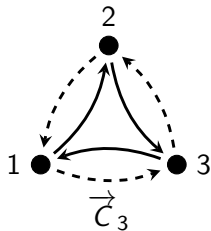
The \mathcal{F} -free orientation problem

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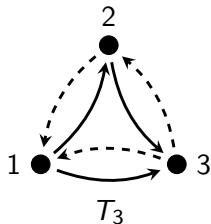
$$\begin{aligned}x_{12} &= 1, & x_{13} &= 1, & x_{23} &= 1, & x_{24} &= 1, & x_{34} &= 1 \\x_{21} &= 0, & x_{31} &= 0, & x_{32} &= 0, & x_{42} &= 0, & x_{43} &= 0\end{aligned}$$

The \mathcal{F} -free orientation problem



For each triangle i, j, k the following equality holds:

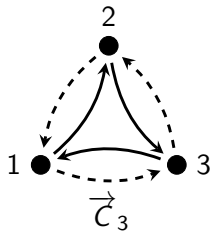
$$x_{ij} + x_{jk} = 0.$$



There exists a triangle i, j, k such that the following equality holds:

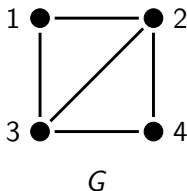
$$x_{ij} + x_{jk} = 1 \text{ for instance } x_{23} + x_{31} = 1.$$

The \mathcal{F} -free orientation problem



For each triangle i, j, k the following equality holds:

$$x_{ij} + x_{jk} = 0.$$

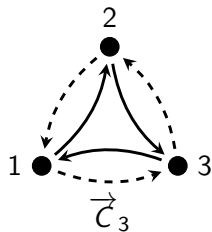


Code T_3 -free orientation of G as solutions to

$$x_{ij} + x_{ji} = 0 \text{ for } ij \in E$$

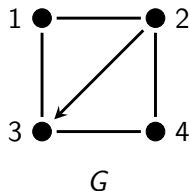
$$x_{ij} + x_{jk} = 0 \text{ for } ijk \in T$$

The \mathcal{F} -free orientation problem



For each triangle i, j, k the following equality holds:

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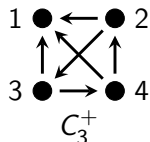
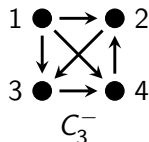
Code T_3 -free orientation completions of G as solutions to

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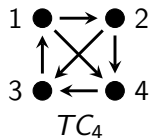
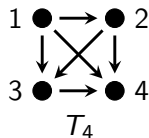
$$x_{ij} = 1 \text{ for } ij \in A$$

The \mathcal{F} -free orientation problem



For each i, j, k, l in C_3^- and in C_3^+

$$x_{ij} + x_{jk} + x_{kl} + x_{li} = 1.$$



$$x_{12} + x_{24} + x_{43} + x_{31} = 0 \text{ in } T_4$$

$$x_{12} + x_{24} + x_{43} + x_{31} = 0 \text{ in } TC_4$$

The \mathcal{F} -free orientation problem

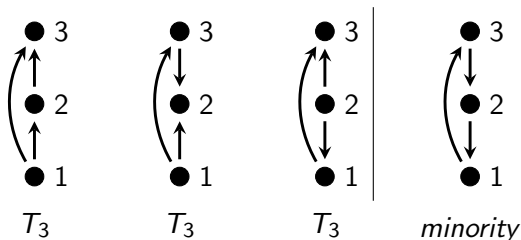
Example 3: The $\{T_4, TC_4\}$ -free orientation (completion) problem is in P

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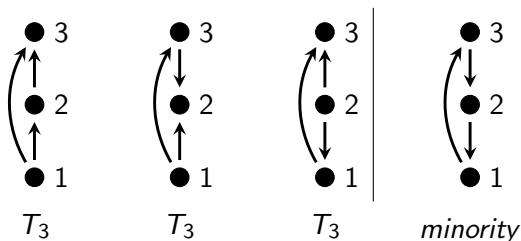
Question: For which finite sets of tournaments \mathcal{F} the \mathcal{F} -free does this method work?

The \mathcal{F} -free orientation problem



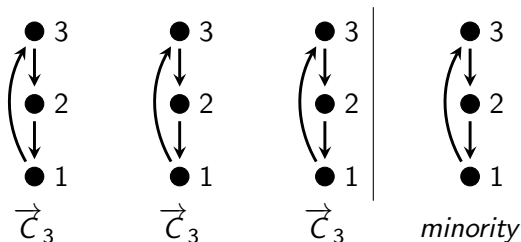
- ▶ \vec{C}_3 -free tournaments **are not** *preserved* by the *minority* operation.
- ▶ T_3 -free tournaments **are** *preserved* by the *minority* operation.

The \mathcal{F} -free orientation problem



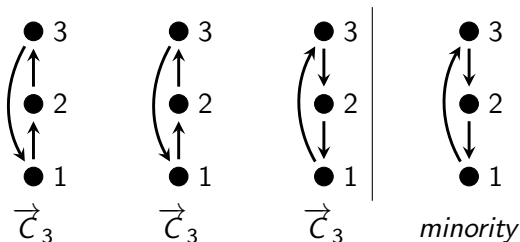
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The \mathcal{F} -free orientation problem



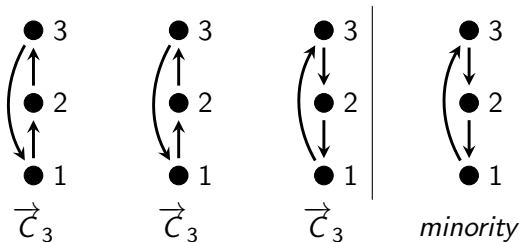
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The \mathcal{F} -free orientation problem



- ▶ \vec{C}_3 -free tournaments **are not** *preserved* by the *minority* operation.
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The \mathcal{F} -free orientation problem



Lemma

Let \mathcal{F} be a finite set of tournaments. The \mathcal{F} -free orientations of a graph G correspond to the solution space of some system of linear equations if and only if the \mathcal{F} -free tournaments are preserved by the minority operation.

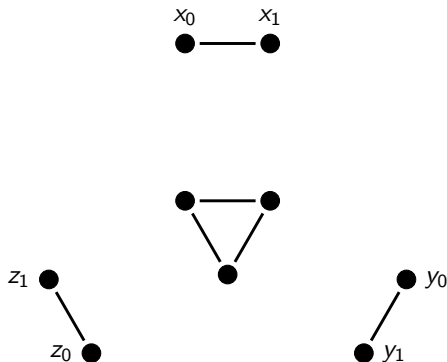
The \mathcal{F} -free orientation problem

Example 4: The \vec{C}_3 -free orientation completion problem is NP-complete

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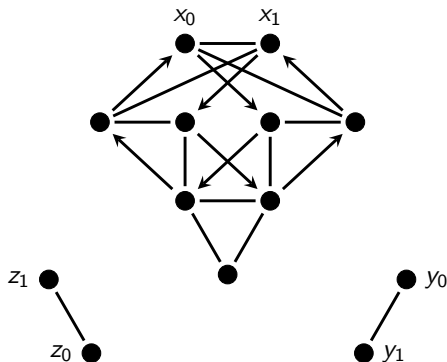
Reduction from NAE 3-SAT with Input: $(x \vee y \vee z) \wedge \dots$



The \mathcal{F} -free orientation problem

Example 4: The \vec{C}_3 -free orientation completion problem is NP-complete

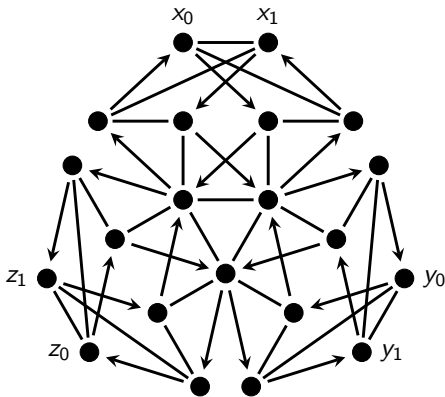
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The \mathcal{F} -free orientation problem

Is that all?

The \mathcal{F} -free orientation problem

Theorem (Bodirsky, G.P., 23+)

For every finite set of finite tournaments \mathcal{F} one of the following cases holds.

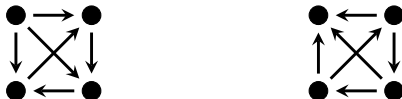
1. \mathcal{F}_f is preserved by the minority operation. In this case, the \mathcal{F} -free orientation completions of a partially oriented graph G correspond to the solution space of a system of linear equations over \mathbb{Z}_2 .
2. Otherwise, \mathcal{F} -free orientation completion problem is NP-complete.

In the first case, the \mathcal{F} -free orientation completion problem is in P.

The \mathcal{F} -free orientation problem

Corollary

If every tournament in \mathcal{F} contains a directed cycle, then the \mathcal{F} -free orientation completion problem is NP-complete.



(Particular instance previously considered by Bang-Jensen, Huang, and Zhu).

The \mathcal{F} -free orientation problem

Theorem (Bodirsky, G.P., 23+)

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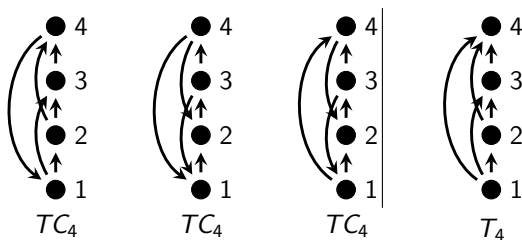
1. \mathcal{F} contains no transitive tournament. In this case, every graph admits an \mathcal{F} -free orientation.
2. \mathcal{F}_f is preserved by the minority operation. In this case, the \mathcal{F} -free orientations of a graph G correspond to the solution space of a system of linear equations over \mathbb{Z}_2 .
3. Otherwise, \mathcal{F} -free orientation problem is NP-complete.

In cases 1 and 2, the \mathcal{F} -free orientation problem is in P.

The \mathcal{F} -free orientation problem

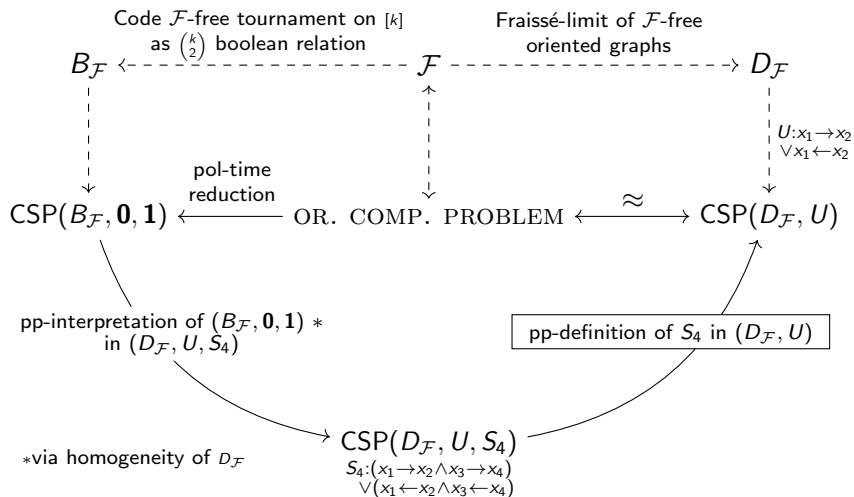
Corollary

The T_k -free orientation problem is NP-complete for each $k \geq 4$.

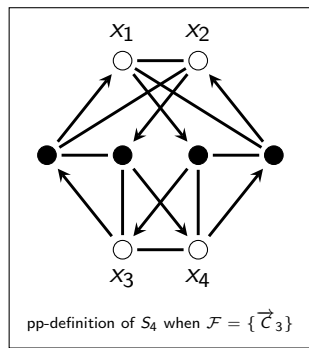


If the \mathcal{F} -free orientation problem is NP-hard, then it is still NP-hard for K_f -free graphs.

Proof overview



Proof overview



Essentially combinatorial

$D_{\mathcal{F}}$

$U: x_1 \rightarrow x_2$
 $\vee x_1 \leftarrow x_2$

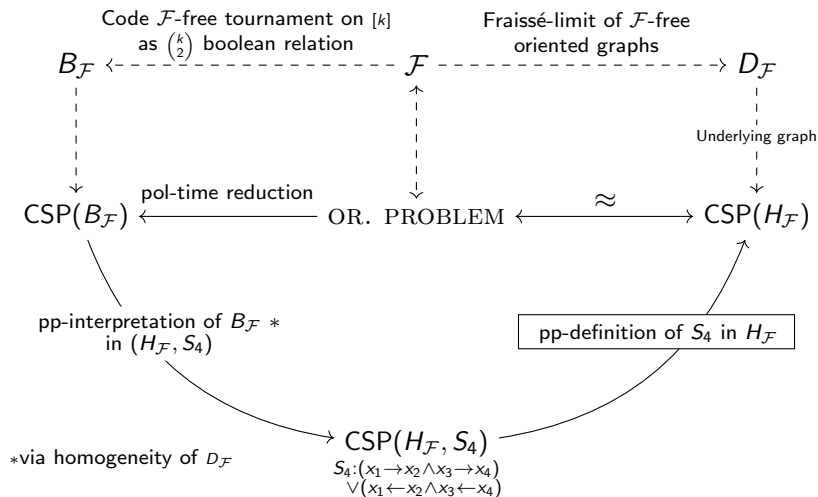
$\text{CSP}(D_{\mathcal{F}}, U)$

pp-definition of S_4 in $(D_{\mathcal{F}}, U)$

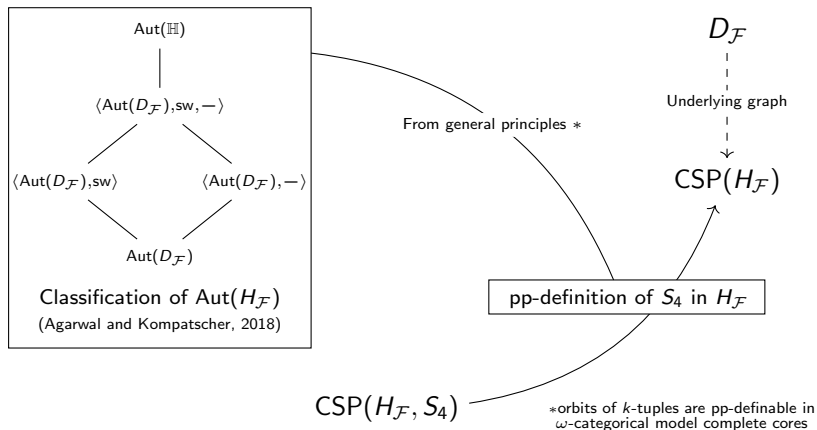
$\text{CSP}(D_{\mathcal{F}}, U, S_4)$

$S_4: (x_1 \rightarrow x_2 \wedge x_3 \rightarrow x_4)$
 $\vee (x_1 \leftarrow x_2 \wedge x_3 \leftarrow x_4)$

Proof overview



Proof overview



Thank you!

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