Valued Constraint Satisfaction Problem and Resilience in Database Theory

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Fixed conjunctive query q. **Input**: a finite database \mathfrak{A} **Output**: minimal number of tuples to be removed from relations of \mathfrak{A} , so that $\mathfrak{A} \not\models q$

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Goal: Classify complexity of resilience for all q.



Fixed τ -structure \mathfrak{A} (τ – finite relational signature) **Input:** list of atomic τ -formulas (constraints) **Output:**

- CSP: Decide whether there is a solution that satisfies all constraints.
- MaxCSP: Find the maximal number of constraints that can be satisfied at once.
- VCSP: Find the minimal cost with which the constraints can be satisfied (each constraint comes with a cost depending on the chosen values).

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Observation: VCSP generalizes CSP and MaxCSP. **Proof:** Model the tuples in relations with cost 0 and outside with cost 1 (for MaxCSP) or ∞ (for CSP).

Focus on VCSP

A valued structure Γ consists of:

- (countable) domain D
- (finite, relational) signature au
- for each $R \in \tau$ of arity k, a function $R^{\Gamma}: D^k \to \mathbb{Q} \cup \{\infty\}$

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Definition (VCSP(Γ))

Input: $u \in \mathbb{Q}$, an expression

$$\phi(x_1,\ldots,x_n)=\sum_i\psi_i,$$

where each ψ_i is an atomic τ -formula **Question:** Is

$$\inf_{\bar{a}\in D^n}\phi(\bar{a})\leq u \text{ in } \Gamma?$$

Example:

Input: G = (V, E) – finite directed graph

Goal: Find a partition $A \cup B$ of V such that $E \cap (A \times B)$ is maximal. Equivalently: $E \cap (A^2 \cup B^2 \cup B \times A)$ is minimal.

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Let Γ_{MC} be a valued structure where:

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$$D = \{0, 1\}$$

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$$\tau = \{R\}$$
, R binary

$$R(x,y) = \begin{cases} 0 \text{ if } x = 0 \text{ and } y = 1\\ 1 \text{ otherwise} \end{cases}$$

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Take vertices of G as variables. The size of a maximal cut of G is

 $\min_{\bar{x}\in D^n}\sum_{(x_i,x_j)\in E} R(x_i,x_j).$ The partition of V is given by the values 0 and 1.

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every instance of VCSP(Γ_{MC}) corresponds to a digraph $\sim VCSP(\Gamma_{MC})$ is the Max-Cut problem (NP-hard)

Example (canonical structure):
$$\exists x, y (R(x, y) \land S(y)) \sim \overset{R}{\underset{x}{\longrightarrow}}$$

For a query q, take its canonical structure \mathfrak{Q} . Search for a structure \mathfrak{B}_q such that for every finite \mathfrak{A} :

$$\mathfrak{A}
ot \models q \, \Leftrightarrow \, \mathfrak{Q}
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Example: For every finite directed graph *G* we have:

$$A \not\rightarrow G \Leftrightarrow G \rightarrow \uparrow$$

 \sim existence of \mathfrak{B}_q enables studying resilience of q using the results about (valued) constraint satisfaction problems

Existence of dual structures

Example (incidence graph): $q := \exists x, y, z(R(x, y) \land R(y, z))$



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A conjunctive query q has a finite dual if and only if I(q) is a tree.

Theorem (Cherlin, Shelah, Shi ('99))

If I(q) is connected, then q has a countable dual \mathfrak{B}_q , which can be chosen so that $\operatorname{Aut}(\mathfrak{B}_q)$ is oligomorphic.

oligomorphic – countable domain B_q and the action of $Aut(\mathfrak{B}_q)$ on B_q^n has finitely many orbits for every $n \ge 1$

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Remark: We have to consider bag databases – a database \mathfrak{A} might contain a tuple with multiplicity > 1 (differs from the original setting). **Example:** Input R(x, y) + R(x, y) for VCSP(Γ) corresponds to a database with multiplicity 2 for R(x, y).

Theorem (Bodirsky, Lutz, S.)

The resilience problem for q equals $VCSP(\Gamma_q)$.

Example: $q := \exists x, y, z(R(x, y) \land R(y, z))$ For every finite *G*:

$$\mathfrak{Q} = \oint \mathcal{A} \; G \; \Leftrightarrow \; G \to \oint = \mathfrak{B}_q$$

 $\mathfrak{B}_q \sim \Gamma_{MC} = (\{0, 1\}; R)$ Resilience of $q = VCSP(\Gamma_{MC}) = Max-Cut$ is NP-hard

Corollary: I(q) is a tree $\Rightarrow \Gamma_q$ can be taken finite

Corollary: l(q) is a tree $\Rightarrow \Gamma_q$ can be taken finite Follows from results of: Kozik, Ochremiak ('15); Kolmogorov, Rolínek, Krokhin ('15); Bulatov ('17); Zhuk ('17)

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For a finite-domain valued structure Γ , VCSP(Γ) is in P or NP-complete.

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Generalisation: theorem holds for q with acyclic I(q)**Question:** For general queries, choose \mathfrak{B}_q such that $\operatorname{Aut}(\mathfrak{B}_q)$ is oligomorphic \Rightarrow finitely many orbits of *n*-tuples for every *n*. Can we use some results for finite domains? pp-construction – a notion of 'expressing' one valued structure in another (generalizes pp-constructions for classical structures)

Fact: If Aut(Γ) is oligomorphic and Γ pp-constructs Δ , then VCSP(Δ) reduces to VCSP(Γ) in poly-time.

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 K_3 is the valued structure on $\{0, 1, 2\}$ with single binary relation E defined:

$$E(x,y) = \begin{cases} 0 \text{ if } x \neq y \\ \infty \text{ if } x = y \end{cases}$$

Observation: VCSP(K_3) is the 3-colorability problem and hence NP-hard.

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Corollary

If $Aut(\Gamma)$ is oligomorphic and Γ pp-constructs K_3 , then $VCSP(\Gamma)$ is NP-hard.

polymorphism f of \mathfrak{B} – an operation $f : B^n \to B$ that preserves all relations of \mathfrak{B} Idea: CSP(\mathfrak{B}) is tractable iff it has nice polymorphisms polymorphism f of \mathfrak{B} – an operation $f : B^n \to B$ that preserves all relations of \mathfrak{B} Idea: CSP(\mathfrak{B}) is tractable iff it has nice polymorphisms

Definition (fractional polymorphism)

 Γ – valued τ -structure with domain D

A fractional polymorphism of Γ of arity *n* is a probablity distribution ω on operations $D^n \to D$ such that for every *k*-ary $R \in \tau$ and $a^1, \ldots, a^n \in D^k$

$$\underbrace{E_{\omega}[f \mapsto R(f(a^{1}, \dots, a^{n}))]}_{\text{expected value}} \leq \underbrace{\frac{1}{n} \sum_{j=1}^{n} R(a^{j})}_{\text{arithmetic mean}} .$$

Tractability conjecture

Known for finite-domain VCSPs:

Theorem

- Γ a finite-domain valued structure
 - If Γ does not pp-construct K₃, then Γ has cyclic fractional polymorphism (essentially Kozik, Ochremiak ('15)).
 - If Γ has a cyclic fractional polymorphism, then VCSP(Γ) is in P (Kolmogorov, Krokhin, Rolínek ('15)).

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If Γ_q has a fractional polymorphism which is canonical and pseudo cyclic with respect to Aut(Γ_q), then VCSP(Γ_q) is in P.

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Conjecture: If Γ_q does not pp-construct K_3 , then the tractability theorem applies and VCSP(Γ_q) and hence resilience of q is in P.

Examples

- $q_{\mathsf{MC}} := \exists x, y, z (R(x, y) \land R(y, z))$
- $q_{\text{path}} := \exists x, y, z (R(x, y) \land S(y, z))$
- $q_{\triangle} := \exists x, y, z (R(x, y) \land S(y, z) \land T(z, x))$
- $q_{\mathsf{new}} := \exists x, y \big(S(x) \land R(x, y) \land R(y, x) \land R(y, y) \big)$



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query	complexity	VCSP proof
<i>q</i> мс	NP-hard (FGIM '20)	Max-Cut/pp-constructs K_3
$q_{\sf path}$	P (MG)	binary symmetric frac. polymorphism
$q_{ riangle}$	NP-hard (FGIM '15)	pp-constructs K_3
$q_{\sf new}$	P (BLS)	binary pseudo cyclic frac. polymorphism

References:

- Meliou, Gatterbauer, Moore, Suciu ('10)
- Freire, Gatterbauer, Immerman, Meliou ('15)
- Freire, Gatterbauer, Immerman, Meliou ('20)
- Makhija, Gatterbauer ('22)
- Bodirsky, Lutz, S.

Thank you for your attention

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